

CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

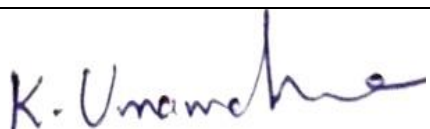
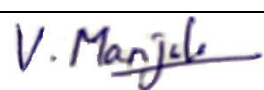
DECLARATION

I hereby certify that the paper entitled **ANFIS PD Plus I Control On Simscape Model of Nonlinear Robotic System** written by the authors **Dr.K.Umamaheswari, Dr.G.Prabhakar, V.Manjula** presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

The citations were updated as per author, year and the spaces are deleted and the paper is in full length of 8 pages.

Date: 21.02.2020

Original signature of the first author

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