

CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitled: **Adaptive LOS Path Following based Enhanced Trajectory Linearization Control for Unmanned Surface Vehicle with Multiple Disturbances and Input Saturation** written by the authors: **Bingbing Qiu, Guofeng Wang, Yunsheng Fan, Dongdong Mu and Xiaojie Sun** presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

29 - 8- 2018

Date

Original signature of the first author

Bingbing Qiu

On completion, please upload the original form on the site <http://ceai.srait.ro>
Control Engineering and Applied Informatics Journal