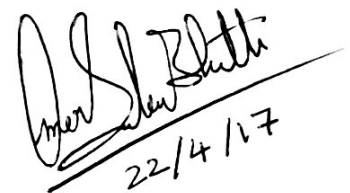


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DECLARATION

I hereby certify that the paper entitled Adaptive Collaborative Position Control of a Tendon-Driven Robotic Finger written by the authors Omer Saleem, Faisal Abbas, Muhammad Usman Khan, Muhammad Anas Imtiaz, Salman Khaid presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

22nd April, 2017.
Date



22/4/17

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