

CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitled "*Tracking Control of A Human Swing Leg as a Double-Pendulum Considering Self-Impact Joint Constraint by Feedback Linearization Method*" written by the authors **Yousef Bazargan-Lari**, **Mohammad Eghtesad**, **Ahmadreza Khoogar** and **Alireza Mohammad-Zadeh** presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

Feb., 11, 2014
Date

Original signature of the first author

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