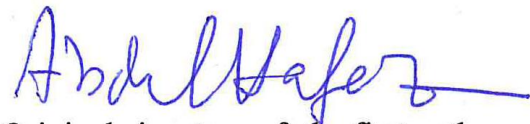


DECLARATION

I hereby certify that the paper entitled “**Visual Servo Control by Optimizing Hybrid Objective Function with Visibility and Path Constraints**”, written by the author **A. H. Abdul Hafez** presents the original results of my research activity. We warrant that the above work has not been previously published elsewhere.

March 24, 2014

Date



Original signature of the first author

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